



NPTEL ONLINE CERTIFICATION COURSES

FINITE ELEMENT METHOD

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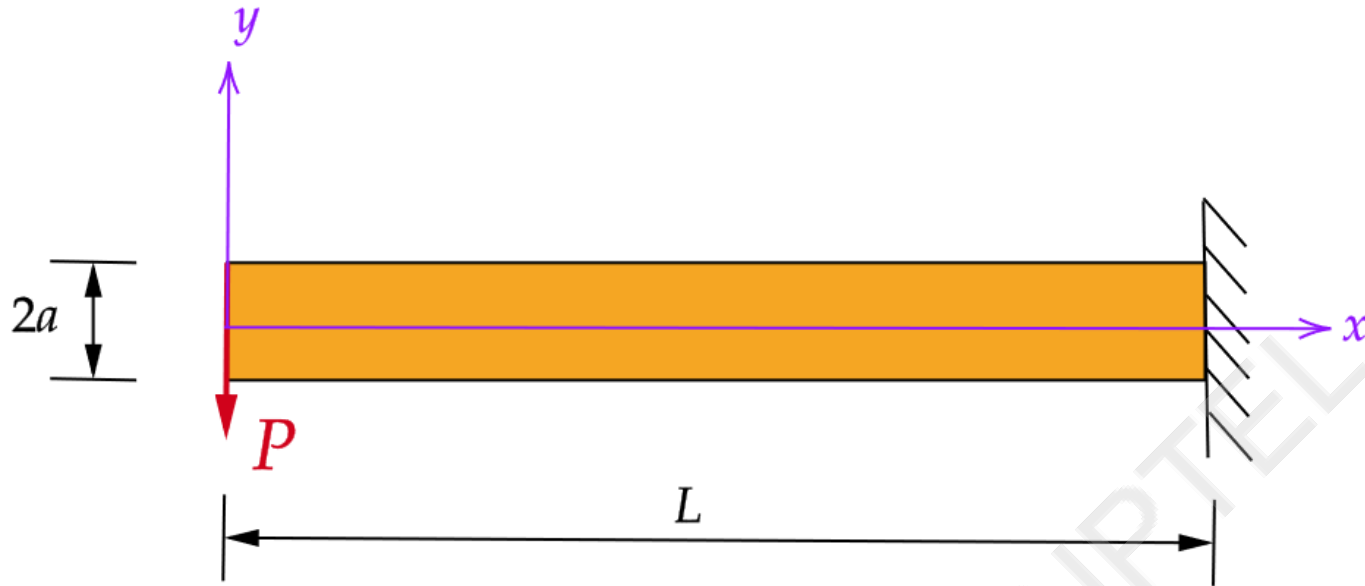
Module 11: Locking

Lecture 52 : Shear Locking

Concepts Covered

- Locking in 1D beam
- Parasitic Shear in Q4 – Shear locking

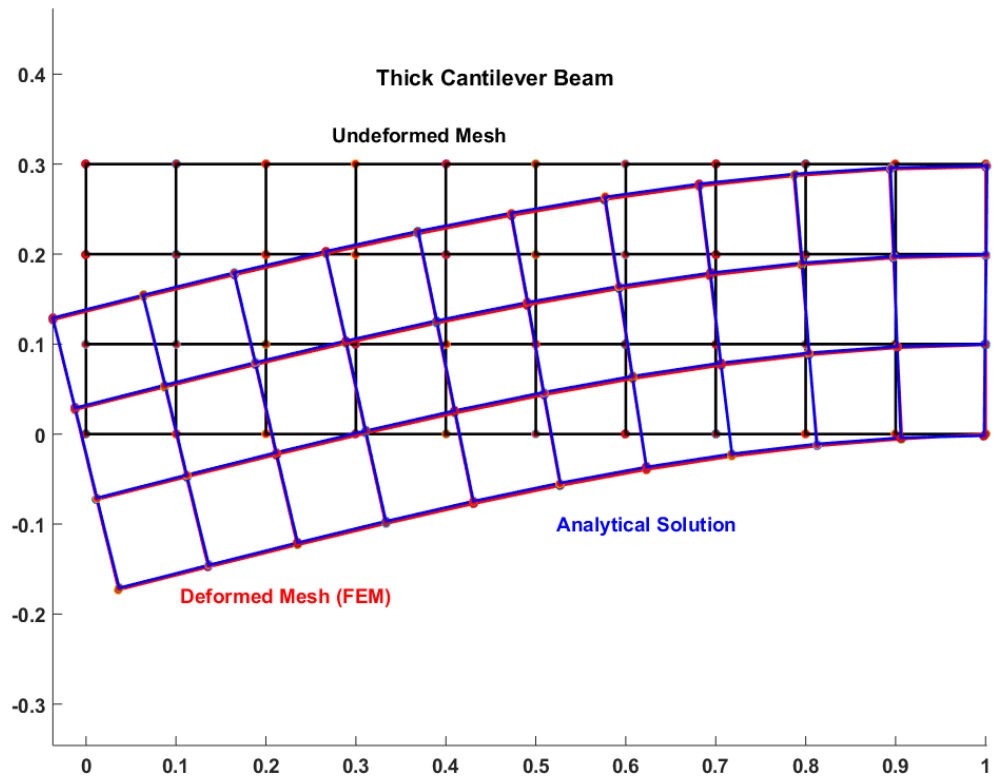
Cantilever Beam Problem



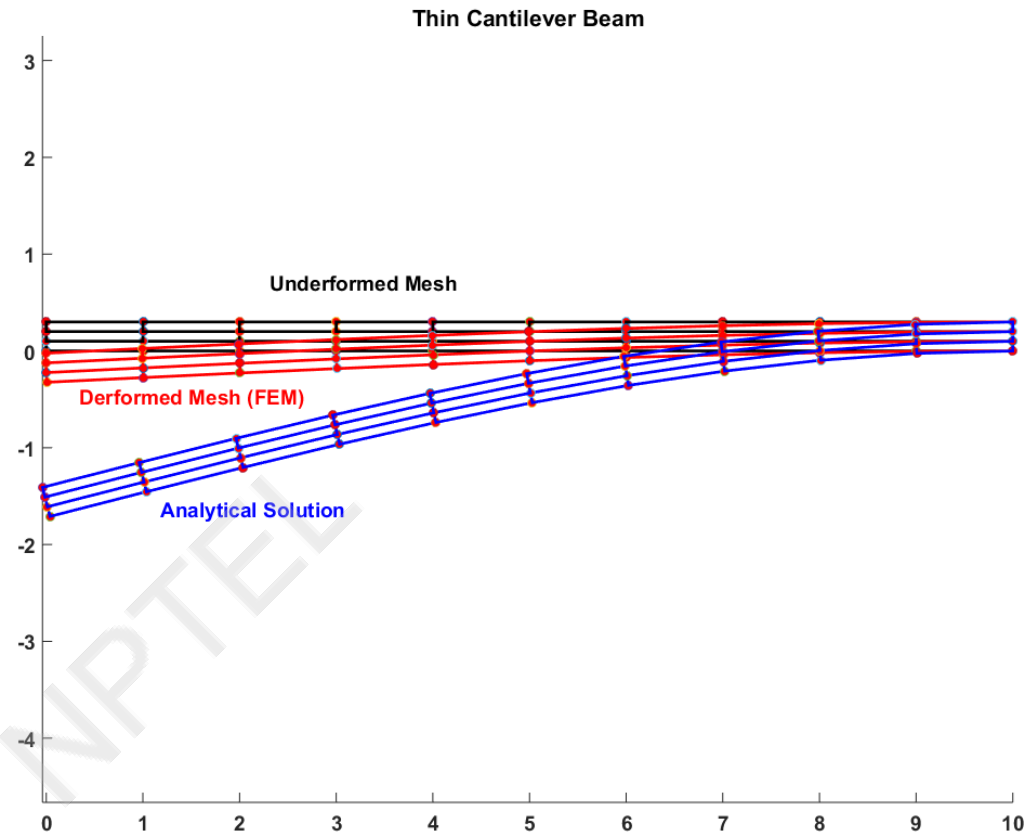
$$u(x, y) = \frac{Px^2y}{2EI} + \nu \frac{Py^3}{6EI} - \frac{Py^3}{6IG} - \left(\frac{PL^2}{2EI} - \frac{Pa^2}{2IG} \right) y$$

$$v(x, y) = -\nu \frac{Px^2y}{2EI} - \frac{Px^3}{6EI} + \frac{PL^3x}{2EI} - \frac{PL^3}{3EI}$$

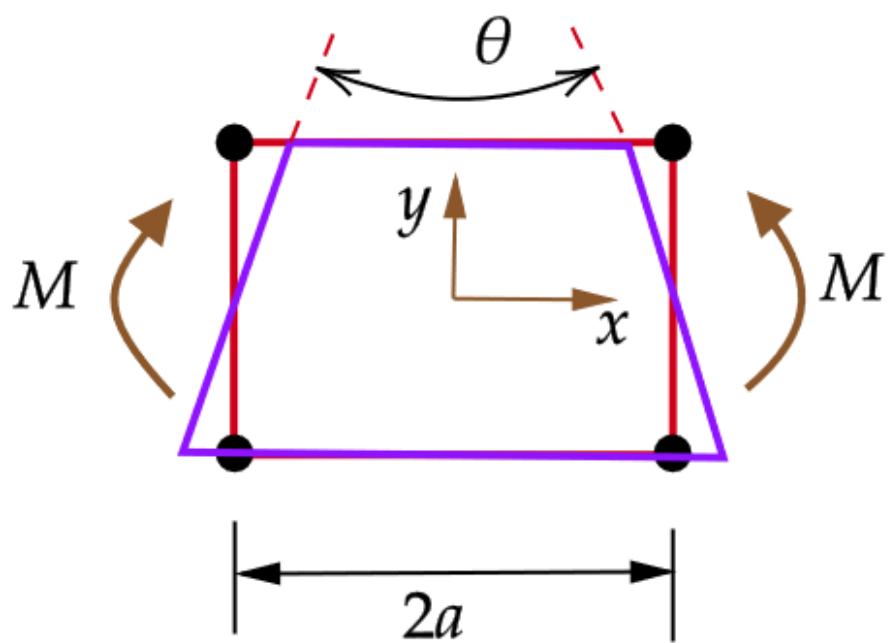
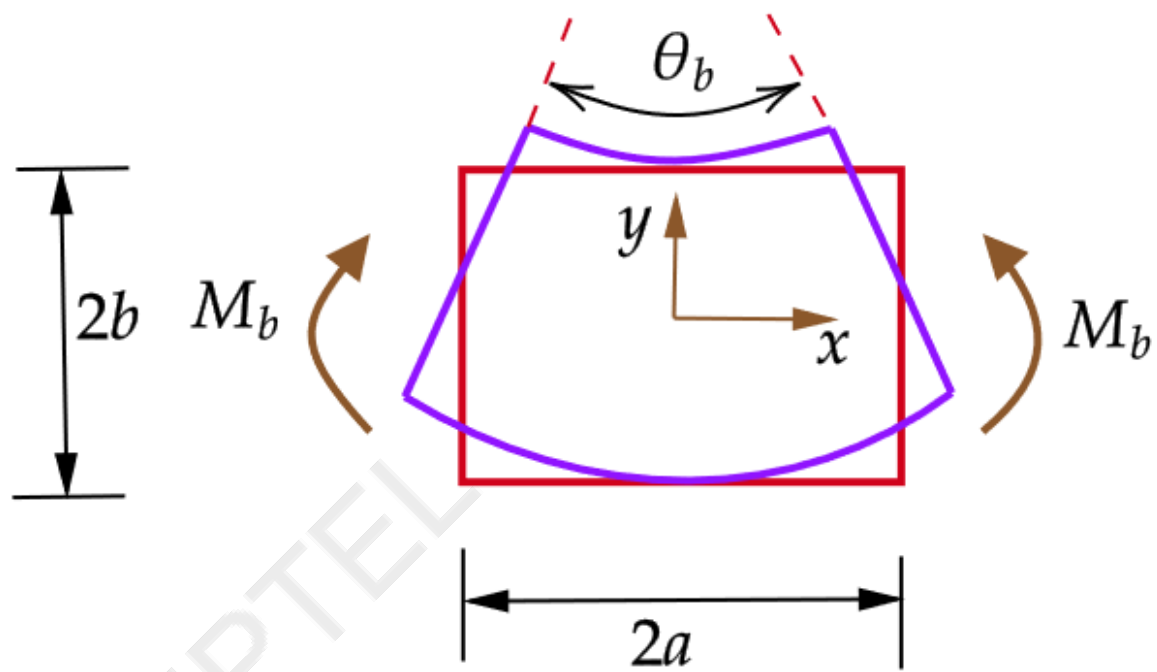
Timoshenko & Goodier



$$a/L = 0.15$$



$$a/L = 0.015$$





FB → thin beam

$$\theta = \frac{dw}{dx}$$

$$u(x, y, z) = -y\theta(x)$$

$$v(x, y, z) = w(x)$$

$$w(x) = (1 - \frac{x}{L})w_1 + \frac{x}{L}w_2$$

$$\theta(x) = (1 - \frac{x}{L})\theta_1 + \frac{x}{L}\theta_2$$

$$\frac{dw}{dx} = \frac{w_2 - w_1}{L} = \text{const.}$$

$$\epsilon_{xx} = \frac{\partial u}{\partial x} = -y \frac{d\theta}{dx}$$

$$\epsilon_{yy} = 0$$

$$\gamma_{xy} = \frac{dw}{dx} = \theta(x)$$

$$\sigma_{xx} = -E y \frac{d\theta}{dx}$$

$$\sigma_{yy} = 0$$

$$\sigma_{xy} = E \theta \left(\frac{dw}{dx} - \theta \right)$$

$$U = U_b + U_s$$

$$= \frac{1}{2} \int_0^L E I \left(\frac{d\theta}{dx} \right)^2 dx + \frac{K_S G A}{2} \int_0^L \left(\frac{dw}{dx} - \theta \right)^2 dx$$

$$= \frac{E b h^3}{24} \int_0^L \left(\frac{d\theta}{dx} \right)^2 dx + \frac{K_S G b h}{2} \int_0^L \left(\frac{dw}{dx} - \theta \right)^2 dx$$



$$w(x) = \frac{x}{L} w_2$$

$$\theta(x) = \frac{x}{L} \theta_2$$

$$U_b = \frac{E b h^3}{24} \int_0^L \frac{\theta_2^2}{L^2} dx = \frac{E b h^3 \theta_2^2 L}{24 L^3} = \frac{E b h^3 \theta_2^2}{24 L}$$

$$U_s = \frac{K_S G b h}{2} \int_0^L \left(\frac{w_2}{L} - \frac{x \theta_2}{L} \right)^2 dx = \frac{K_S G b h}{2 L^3} \int_0^L (w_2^2 + x^2 \theta_2^2 - 2 x w_2 \theta_2) dx$$

$$= \frac{K_S G b h}{2 L^3} \left(w_2^2 L + \frac{L^3 \theta_2^2}{3} - L^2 w_2 \theta_2 \right)$$

$$\Pi = \frac{E b h^3 \theta_2^2}{24 L} + \frac{K_S G b h}{2 L^3} \left(w_2^2 L + \frac{L^3 \theta_2^2}{3} - L^2 w_2 \theta_2 \right) - P w_2$$

$$\frac{\partial \Pi}{\partial w_2} = 0, \quad \frac{\partial \Pi}{\partial \theta_2} = 0$$

$$\frac{\partial \Pi}{\partial w_2} = 0 = \frac{K_S G b h}{2 L^2} (2 w_2 L - L^2 \theta_2) - P = 0 \quad \text{--- (A)}$$

$$\frac{\partial \Pi}{\partial \theta_2} = 0 = \frac{E b h^3 \theta_2}{24 L} + \frac{K_S G b h}{2 L^2} \left(\frac{2}{3} \theta_2 L^3 - L^2 w_2 \right) = 0 \quad \text{--- (B)}$$

$$\text{from (A)} \rightarrow \theta_2 = \frac{K_S G b h}{2 L} w_2 \left[\frac{1}{\frac{E b h^3}{24 L^2} + \frac{K_S G b h}{2}} \right] = \frac{K_S G A}{2 L} w_2 \left[\frac{1}{\frac{E A}{12} \left(\frac{h}{L} \right)^2 + \frac{K_S G A}{2}} \right]$$

Sub. θ_2 in (B) →

$$w_2 = \left(\frac{E (h/L)^2 + 4 K_S G A}{E (h/L)^2 + K_S G A} \right) \frac{P L}{K_S G A}$$

Thin beam $\frac{h}{L} \ll 1$

$$\frac{h}{L} = 0$$

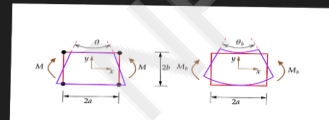
$$w_2 = 4 \left(\frac{P L}{K_S G A} \right) = 4 \cdot 8 \frac{P L}{G A}$$

$$K_S = \frac{5}{L}$$

Thick beam $\frac{h}{L} \approx 1$

$$\frac{h}{L} \approx 1$$

$$w_2 = \left(\frac{E + 4 K_S G A}{E + K_S G A} \right) \frac{P L}{K_S G A}$$



Approx.

$$\bar{u} = \frac{y}{2} \theta$$

$$u(x, y) = -\frac{x y}{a b} \theta = -\frac{x y \theta}{2 a}$$

$$v(x, y) = 0$$

$$\epsilon_{xx} = -\frac{\partial u}{\partial x} = \frac{y \theta}{2 a}$$

$$\epsilon_{yy} = 0$$

$$\gamma_{xy} = -\frac{\partial u}{\partial y} = \frac{x \theta}{2 a}$$

$$\begin{Bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{xy} \end{Bmatrix} = \frac{E}{1-\nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{1-\nu}{2} \end{bmatrix} \begin{Bmatrix} \epsilon_{xx} \\ \epsilon_{yy} \\ \gamma_{xy} \end{Bmatrix}$$

$$\begin{Bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{xy} \end{Bmatrix} = \begin{Bmatrix} \epsilon_{xx} \\ \epsilon_{yy} \\ \gamma_{xy} \end{Bmatrix} \begin{Bmatrix} E_{xx} \\ E_{yy} \\ E_{xy} \end{Bmatrix}$$

$$\begin{Bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{xy} \end{Bmatrix} = \begin{Bmatrix} -\frac{E y \theta}{2 a} \\ 0 \\ \frac{E x \theta}{2 a} \end{Bmatrix}$$

$$U_a = \frac{1}{2} \int_V \{\sigma\}^T \{\epsilon\} dV$$

$$= \frac{1}{2} \iiint \left(\frac{E}{1-\nu^2} \epsilon_{xx}^2 + \frac{E}{1-\nu^2} \epsilon_{yy}^2 + \frac{E}{1-\nu^2} \gamma_{xy}^2 \right) dx dy dz$$

$$= \frac{1}{2} \frac{E h}{1-\nu^2} \int_{-b}^b \int_{-a}^a \left(\frac{\partial^2 y}{\partial x^2} + \frac{E}{1-\nu^2} \cdot \frac{h}{2} \cdot \frac{1-\nu}{2} \int_{-b}^b \int_{-a}^a \frac{\partial^2 x}{\partial y^2} dx dy \right) dx dy$$

$$= \frac{E h b^3 \theta^2}{6 a (1-\nu^2)} + \frac{E}{1-\nu^2} \left(\frac{a b h (1-\nu)}{12} \theta^2 \right)$$

$$U_{exact} = \frac{1}{2} \int \{\sigma\}^T \{\epsilon\} dV$$

$$= \frac{1}{2} \int_{-b}^b \int_{-a}^a \int_{-c}^c E \epsilon_{xx}^2 dx dy dz$$

$$= \frac{1}{2} \int_{-b}^b \int_{-a}^a E \left(\frac{\partial^2 y}{\partial x^2} \right)^2 dx dy$$

$$= \frac{E b h^3 \theta^2}{6 a}$$

$$\frac{U_{approx}}{U_{exact}} = \frac{\frac{E h b^3 \theta^2}{6 a (1-\nu^2)} + \frac{E}{1-\nu^2} \left(\frac{a b h (1-\nu)}{12} \theta^2 \right)}{\frac{E b h^3 \theta^2}{6 a}}$$

$$= \frac{\theta^2}{\theta_0^2} \frac{1}{1+\nu} \left[\frac{1}{1-\nu} + \frac{1}{2} \left(\frac{a}{b} \right)^2 \right]$$

$$\frac{M}{M_b} = \frac{1}{1+\nu} \left[\frac{1}{1-\nu} + \frac{1}{2} \left(\frac{a}{b} \right)^2 \right]$$

$$u = x_0 + a_1 x + a_2 y + a_3 x y$$

$$v = b_0 + b_1 x + b_2 y + b_3 x y$$

$$Exact: \quad \bar{u} = \frac{b y}{2}$$

$$u(x, y) = -\frac{x y}{2 a} \theta_0$$

$$v(x, y) = -\left(1 - \frac{x^2}{a^2}\right) \frac{a}{2 b} \frac{b y}{2}$$

$$+ \theta \left(1 - \frac{y^2}{b^2}\right) \frac{b}{2 a} \frac{b y}{2}$$

$$\epsilon_{xx} = -\frac{\partial u}{\partial x} = \frac{y \theta}{2 a}$$

$$\epsilon_{yy} = \frac{\partial v}{\partial y} = \gamma \epsilon_{xx}$$

$$\gamma_{xy} = 0$$

$$\sigma_{yy} = 0$$

$$\sigma_{xy} = 0$$



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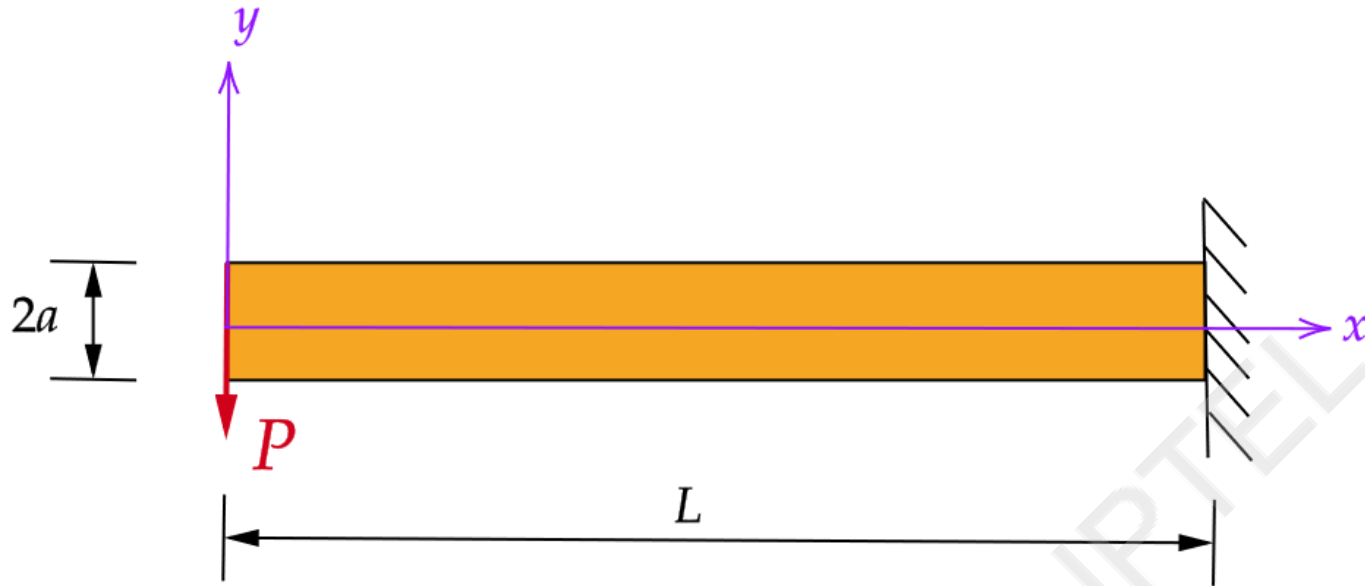
Module 11: Shear Locking

Lecture 53 : Selective reduced Integration and Modes of Q4 Element

Concepts Covered

- Parasitic Shear in Q4 – Shear locking
- Selective Reduced Integration
- Modes of Q4 Element

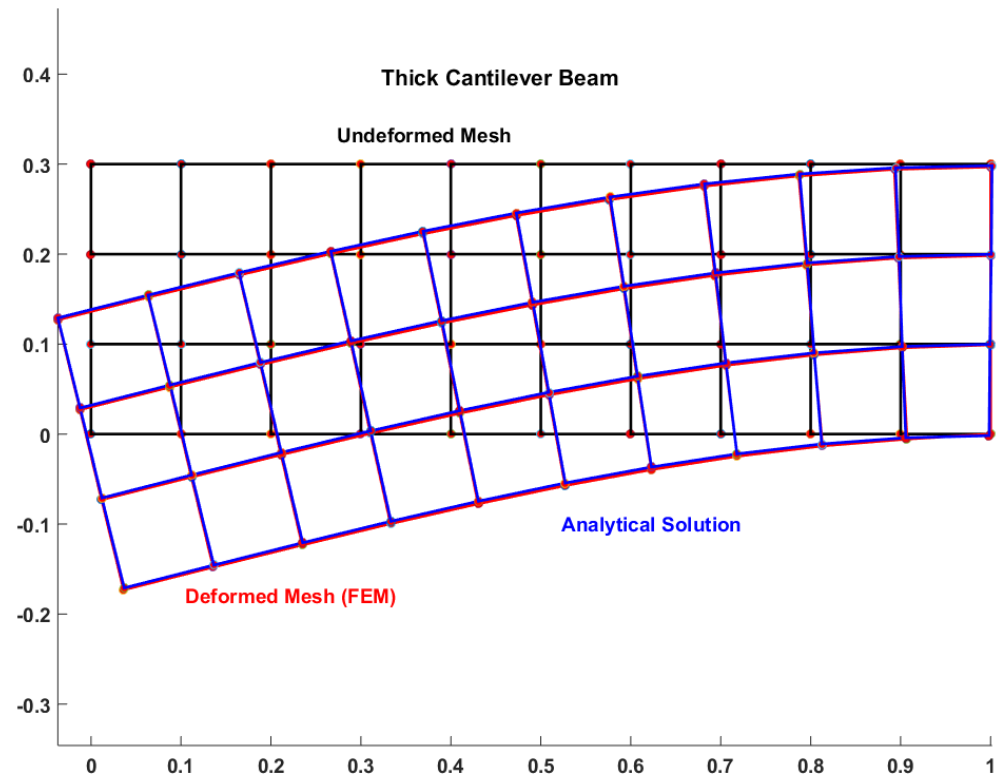
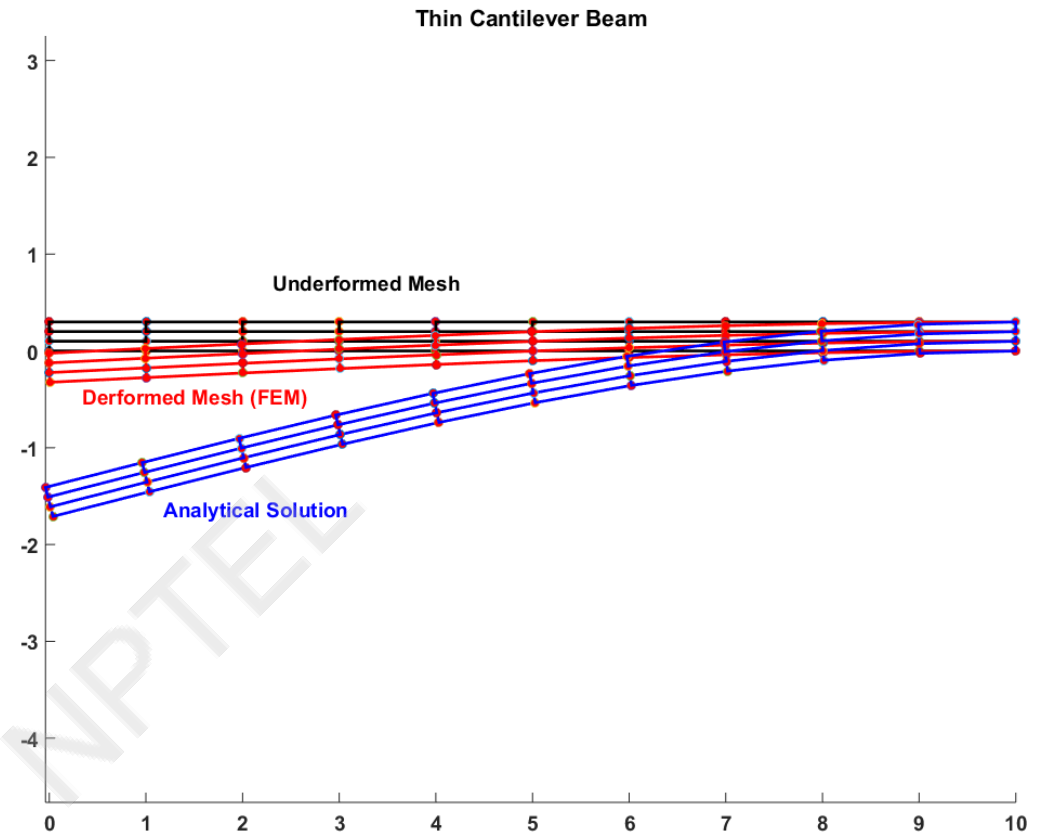
Cantilever Beam Problem



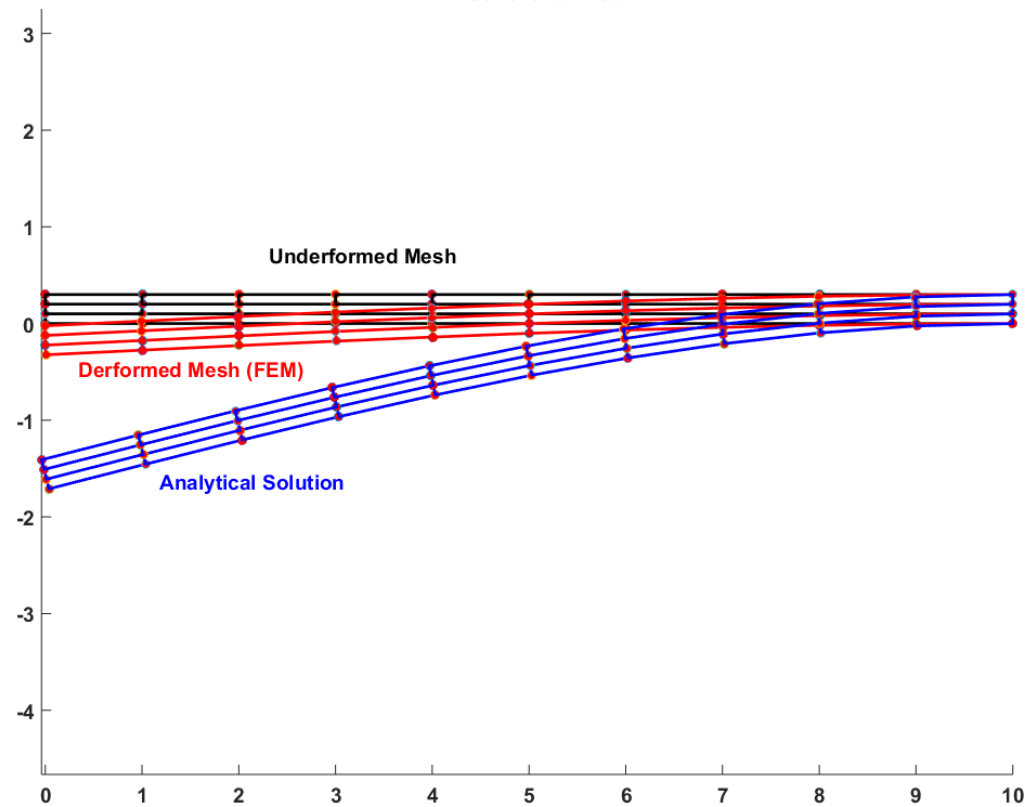
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$$v(x, y) = -\nu \frac{Px^2y}{2EI} - \frac{Px^3}{6EI} + \frac{PL^3x}{2EI} - \frac{PL^3}{3EI}$$

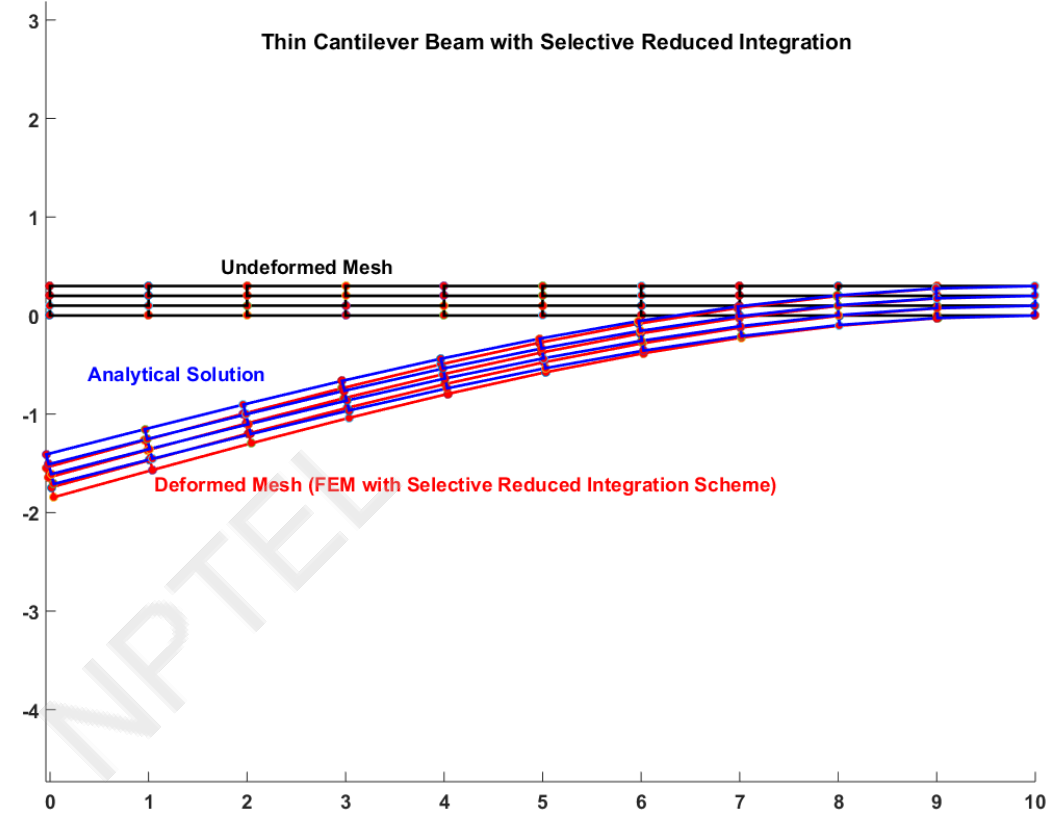
Timoshenko & Goodier

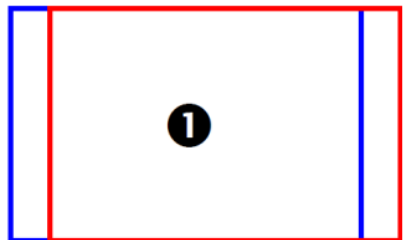
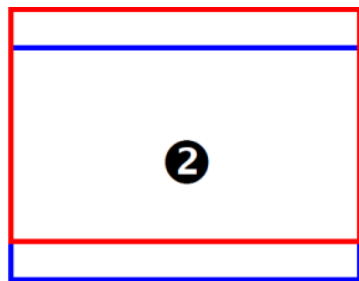
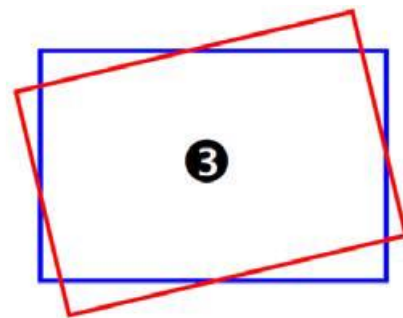
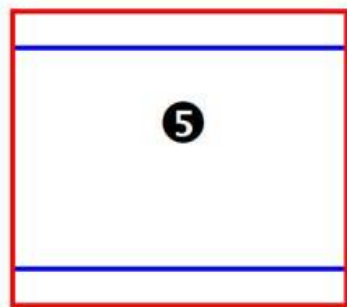
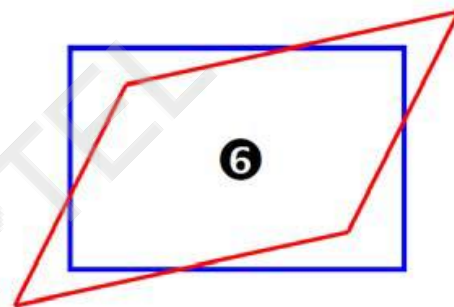
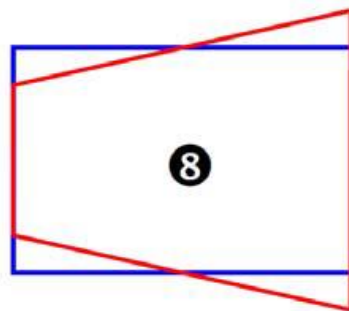


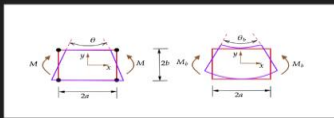
Thin Cantilever Beam



Thin Cantilever Beam with Selective Reduced Integration







$$\begin{matrix} 2b \\ \boxed{} \\ 2a \end{matrix}$$

$$\frac{U_{approx}}{U_{exact}} = \frac{\frac{q^2}{8b^2}}{\frac{q^2}{8b^2}} \cdot \frac{1}{1+\nu} \left[\frac{1}{1-\nu} + \frac{1}{2} \left(\frac{a}{b} \right)^2 \right]$$

$$\frac{M}{M_b} = \frac{1}{1+\nu} \left[\frac{1}{1-\nu} + \frac{1}{2} \left(\frac{a}{b} \right)^2 \right]$$

$$\text{as } \left(\frac{a}{b} \right) \rightarrow \infty \quad \frac{M}{M_b} \rightarrow \infty$$



$$\left. \begin{aligned} \epsilon_{xx} &= -\frac{qy}{2a} \\ \epsilon_{yy} &= 0 \\ \gamma_{xy} &= -\frac{qx}{2a} \end{aligned} \right\}$$

$$\text{at } x=0 \quad \sigma_{xy} = 0 \leftarrow \text{Expected}$$

$$K^e = \int_V B^T C B \, dv$$

$$= \int_V B^T C_b B_b \, dv + \int_V B^T C_s B_s \, dv$$

$$= K_b + K_s$$

$$C = \begin{bmatrix} c_{11} & c_{12} & 0 \\ c_{12} & c_{22} & 0 \\ 0 & 0 & c_{66} \end{bmatrix}$$

$$= \begin{bmatrix} c_{11} & c_{12} & 0 \\ c_{12} & c_{22} & 0 \\ 0 & 0 & c_{66} \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & c_{66} \end{bmatrix}$$

$$\begin{matrix} \boxed{\begin{matrix} x & x \\ x & x \end{matrix}} \xrightarrow{\substack{2 \times 2 \text{ (} \xi, \eta = \pm \frac{1}{2} \text{)} \\ 1 \times 1 \text{ (} \xi=0, \eta=0 \text{)}}} C_b + C_s \end{matrix}$$

$$\begin{aligned} K_b &\rightarrow \text{full integration } 2 \times 2 \\ K_s &\rightarrow \text{reduced integration } 1 \times 1 \end{aligned}$$

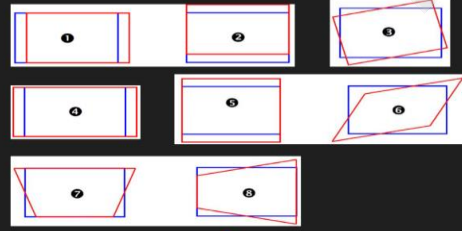
Modes of Q4 Element:-

$$K^e = \int_V B^T C B \, dv \quad \boxed{\begin{matrix} x & x \\ x & x \end{matrix}} \quad 2 \times 2$$

$$\text{full integration. Rank}(K^e) = 8 - 3 \quad \leftarrow \text{no. of rigid body modes.}$$

$$\text{reduced integration Rank} = 8 - 3 - 2 \quad \leftarrow \text{hourglass modes.}$$

$$\rightarrow \det(K - \lambda I) = 0 \rightarrow$$



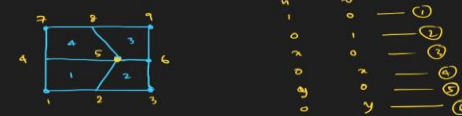
$$\boxed{\begin{matrix} x \\ x \end{matrix}} \quad 1 \times 1$$

$$\boxed{\begin{matrix} x & x \\ x & x \end{matrix}} \quad 2 \times 2$$

$$\text{Eg. version Patch Test}$$

$$U = \frac{1}{2} \int_V \{ \epsilon \}^T [C] \{ \epsilon \} \, dv$$

$$\left. \begin{aligned} ① \rightarrow u=c, v=0 &\rightarrow \epsilon_{xx}=c, \epsilon_{yy}=0, \gamma_{xy}=0 \\ ② \rightarrow u=0, v=c &\rightarrow \epsilon_{xx}=\epsilon_{yy}=0, \gamma_{xy}=0 \\ ③ \rightarrow u=c\eta, v=-c\xi &\rightarrow \epsilon_{xx}=0, \epsilon_{yy}=0, \gamma_{xy}=c-c=0 \\ ④ \rightarrow u=c\xi, v=0 &\rightarrow \epsilon_{xx}=c, \epsilon_{yy}=0, \gamma_{xy}=0 \\ ⑤ \rightarrow u=0, v=c\eta &\rightarrow \epsilon_{xx}=0, \epsilon_{yy}=c, \gamma_{xy}=0 \\ ⑥ \rightarrow u=c\eta, v=c\xi &\rightarrow \epsilon_{xx}=0, \epsilon_{yy}=0, \gamma_{xy}=2c \\ ⑦ \rightarrow u=c\xi\eta, v=0 &\rightarrow \epsilon_{xx}=c\eta, \epsilon_{yy}=0, \gamma_{xy}=c\xi \\ ⑧ \rightarrow u=0, v=c\xi\eta &\rightarrow \epsilon_{xx}=0, \epsilon_{yy}=c\xi, \gamma_{xy}=c\eta \end{aligned} \right\}$$



① displacement at c should be exact.
② gradient of displacement should represent constant strain



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Module 11: Shear Locking

Lecture 54 : Incompatible Elements

Concepts Covered

- What is Incompatible Elements ?
- Q6 and QM6 Element

References:

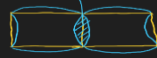
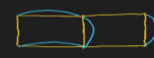
1. Wilson, E. L., R. L. Taylor, W. P. Doherty, and J. Ghaboussi. "Incompatible displacement models." In *Numerical and computer methods in structural mechanics*, pp. 43-57. Academic Press, 1973.
2. Taylor, Robert L., Peter J. Beresford, and Edward L. Wilson. "A non-conforming element for stress analysis." *International Journal for numerical methods in Engineering* 10, no. 6 (1976): 1211-1219.
3. Taylor, R. L., J. C. Simo, O. C. Zienkiewicz, and ACH Chan. "The patch test—a condition for assessing FEM convergence." *International journal for numerical methods in engineering* 22, no. 1 (1986): 39-62.
4. Ibrahimbegovic, Adnan, and E. L. Wilson. "A modified method of incompatible modes." *Communications in Applied Numerical Methods* 7, no. 3 (1991): 187-194.

$u_0 \in \square_{1 \times 2h-4}$
 $u = \frac{1}{4} \eta^2$
 $v = 0$ } Q4 Element

$c_{xx} = 0$
 $c_{yy} = \varphi_{c,yy}$
 $\varphi_{c,yy} = 0$

$u = \frac{1}{4} \eta^2$
 $v = \frac{(1-\eta^2)}{2b} \frac{\partial u}{\partial \eta} + \frac{(1-\eta^2)}{2a} \frac{\partial v}{\partial \xi}$ } exact

$\varphi_i(\xi, \eta) = \frac{1}{4} (1 \mp \xi) (1 \mp \eta) \quad i=1,2,3,4$



Wilson et al. →

$k = \int_{\Omega} B^T C B d\Omega$
 12×12
 12×3
 3×12
 $k = \begin{bmatrix} k_{aa} & k_{ad} \\ k_{da} & k_{dd} \end{bmatrix}$
 $\begin{bmatrix} k_{aa} & k_{ad} \\ k_{da} & k_{dd} \end{bmatrix} \begin{Bmatrix} \Delta \\ d \end{Bmatrix} = \begin{Bmatrix} F \\ 0 \end{Bmatrix}$

$B = \begin{bmatrix} B_1 & B_2 & B_3 & B_4 & B_5 & B_6 \end{bmatrix}$
 5×12
 $d = \begin{Bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \\ u_5 \\ u_6 \end{Bmatrix}$
 $d = \begin{Bmatrix} d_1 \\ d_2 \\ d_3 \\ d_4 \end{Bmatrix}$

$k_{aa} = \int_{\Omega} B_a^T C B_a d\Omega$
 12×3
 3×3
 3×3
 $[k_{aa}] \{ \Delta \} + [k_{ad}] \{ d \} = 0$
 $\Rightarrow \{ d \} = -[k_{ad}]^{-1} [k_{aa}] \{ \Delta \}$
 $[k_{aa}] \{ \Delta \} + [k_{ad}] \{ d \} = \{ F \}$
 $\Rightarrow [k_{aa}] \{ \Delta \} - [k_{ad}] [k_{ad}]^{-1} [k_{aa}] \{ \Delta \} = \{ F \}$
 $\Rightarrow [k_{ee}] \{ \Delta \} = \{ F \}$
 $[k_{ee}] \{ \Delta \} = \{ F \}$

Completeness condition Q4

$u = \sum \varphi_i u_i$
 $= \sum \varphi_i (c_0 + c_1 \eta_i + c_2 \eta_i^2)$
 $= (\sum \varphi_i) c_0 + (\sum \varphi_i \eta_i) c_1 + (\sum \varphi_i \eta_i^2) c_2$
 $= c_0 + c_1 \eta + c_2 \eta^2$

$u_i = c_0 + c_1 \eta_i + c_2 \eta_i^2$

$\eta = \sum \varphi_i \eta_i$
 $\eta = \sum \varphi_i \eta_i$

$\begin{bmatrix} k_{aa} & k_{ad} \\ k_{da} & k_{dd} \end{bmatrix} \begin{Bmatrix} \Delta \\ d \end{Bmatrix} = \begin{Bmatrix} F \\ 0 \end{Bmatrix}$
 $\frac{k_{da} \Delta + k_{dd} d}{0} = 0$

$[k_{da}] \{ \Delta \} = \int B_a^T C B d\Omega \{ d \} = 0$
 $B = \begin{bmatrix} B_1 & B_2 & B_3 & B_4 & B_5 & B_6 \end{bmatrix}$
 3×6
 3×4
 $\int B_a^T C B d\Omega \{ d \} = 0$
 $\Rightarrow \int B_a^T \{ 0 \} d\Omega = 0$
 $\Rightarrow \int B_a^T d\Omega \{ 0 \} = 0$

$\int B_a^T d\Omega = 0$
 $\Rightarrow \int [B_5 \ B_6]^T d\Omega = 0$
 $\int B_5 d\Omega = 0$
 $\int B_6 d\Omega = 0$

$= \int \begin{bmatrix} \varphi_{c,\eta} & 0 \\ 0 & \varphi_{c,\eta} \end{bmatrix} d\eta$
 $= \int \begin{bmatrix} \varphi_{c,\eta} & 0 \\ 0 & \varphi_{c,\eta} \end{bmatrix} d\eta$
 $= \int \begin{bmatrix} \varphi_{c,\eta} & 0 \\ 0 & \varphi_{c,\eta} \end{bmatrix} d\eta$
 $= \int \begin{bmatrix} \varphi_{c,\eta} & 0 \\ 0 & \varphi_{c,\eta} \end{bmatrix} d\eta$

$\varphi_{c,\eta} = \frac{\partial \varphi_i}{\partial \eta}$

$\varphi_{c,\eta} = (1-\eta^2)$

$B_5 = \begin{bmatrix} \varphi_{c,\eta} & 0 \\ 0 & \varphi_{c,\eta} \end{bmatrix}$

$\begin{bmatrix} \frac{\partial \varphi}{\partial \eta} & \frac{\partial \varphi}{\partial \eta} \\ \frac{\partial \varphi}{\partial \eta} & \frac{\partial \varphi}{\partial \eta} \end{bmatrix} = \frac{1}{3} \begin{bmatrix} \frac{\partial \varphi}{\partial \eta} & -\frac{\partial \varphi}{\partial \eta} \\ -\frac{\partial \varphi}{\partial \eta} & \frac{\partial \varphi}{\partial \eta} \end{bmatrix}$

$B_6 = 1-\eta^2$
 $\int B_6 d\Omega = 0$
 $\Rightarrow \int \begin{bmatrix} \eta \frac{\partial \varphi}{\partial \eta} & 0 \\ 0 & -\eta \frac{\partial \varphi}{\partial \eta} \end{bmatrix} d\eta$

$B_5 = \frac{2}{3} \begin{bmatrix} -\xi \eta, \eta(0,0) & 0 \\ 0 & \xi \eta, \eta(0,0) \end{bmatrix}$
 $B_6 = \frac{2}{3} \begin{bmatrix} \xi \eta, \eta(0,0) & -\xi \eta, \eta(0,0) \\ \eta \eta, \eta(0,0) & -\eta \eta, \eta(0,0) \end{bmatrix}$



**THANK
YOU !**



NPTEL ONLINE CERTIFICATION COURSES

FINITE ELEMENT METHOD

Biswanath Banerjee & Amit Shaw

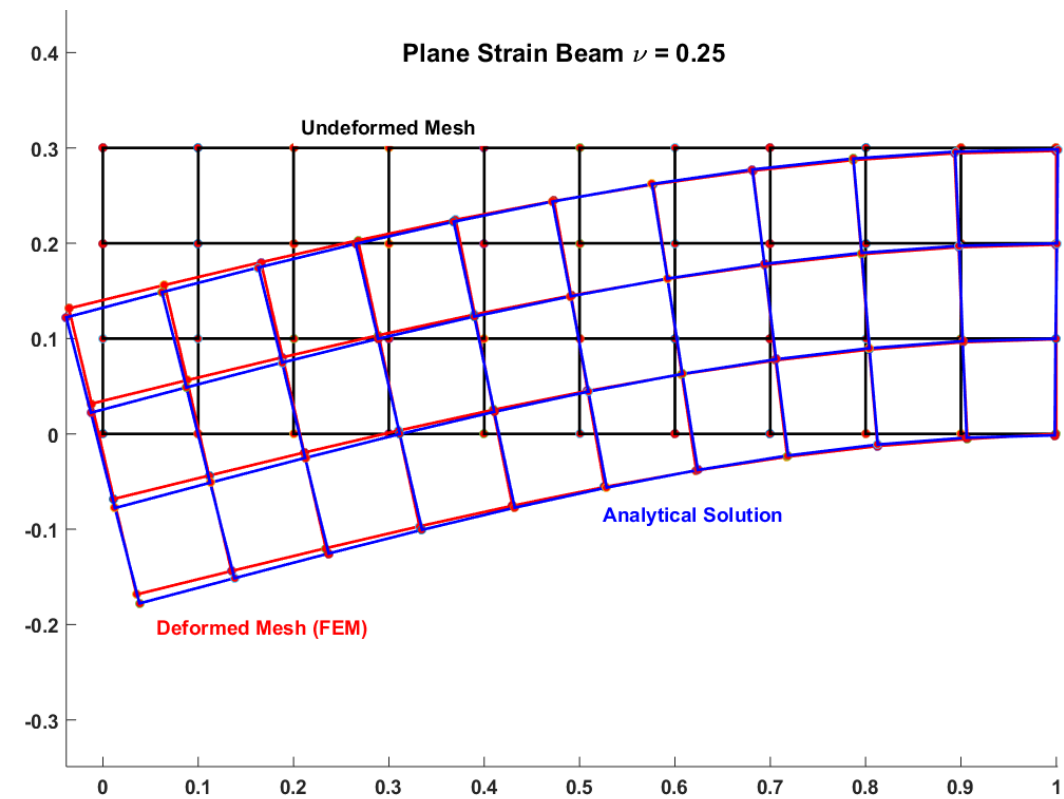
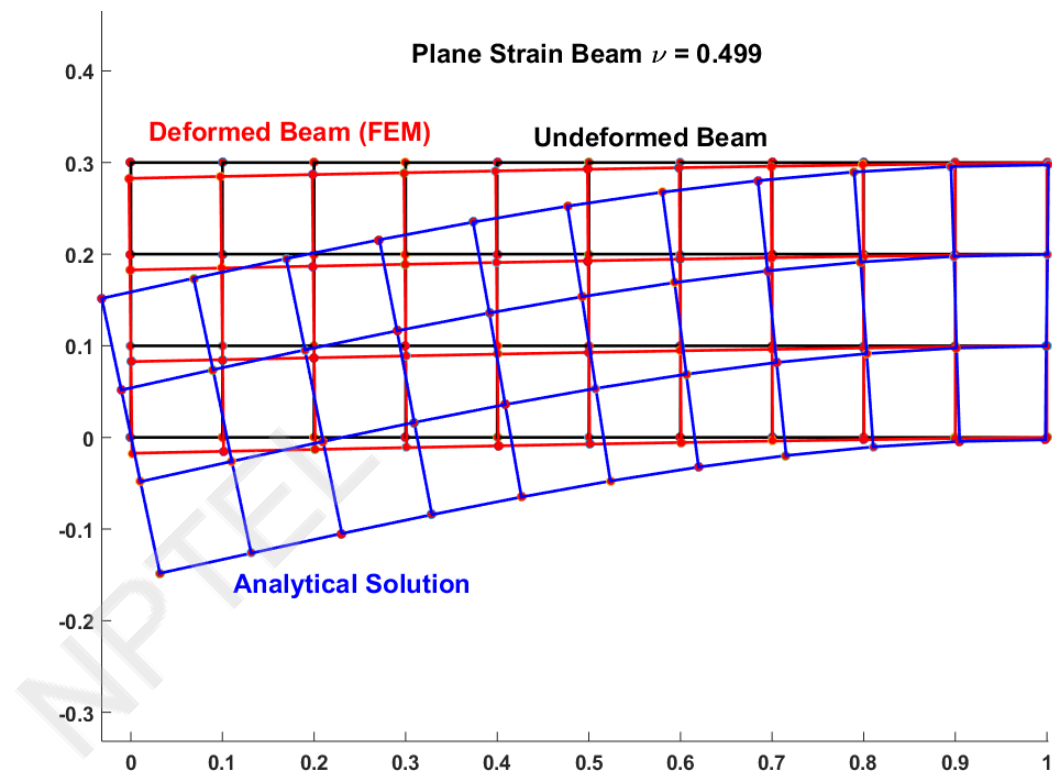
Department of Civil Engineering, IIT Kharagpur

Module 11: Volumetric Locking

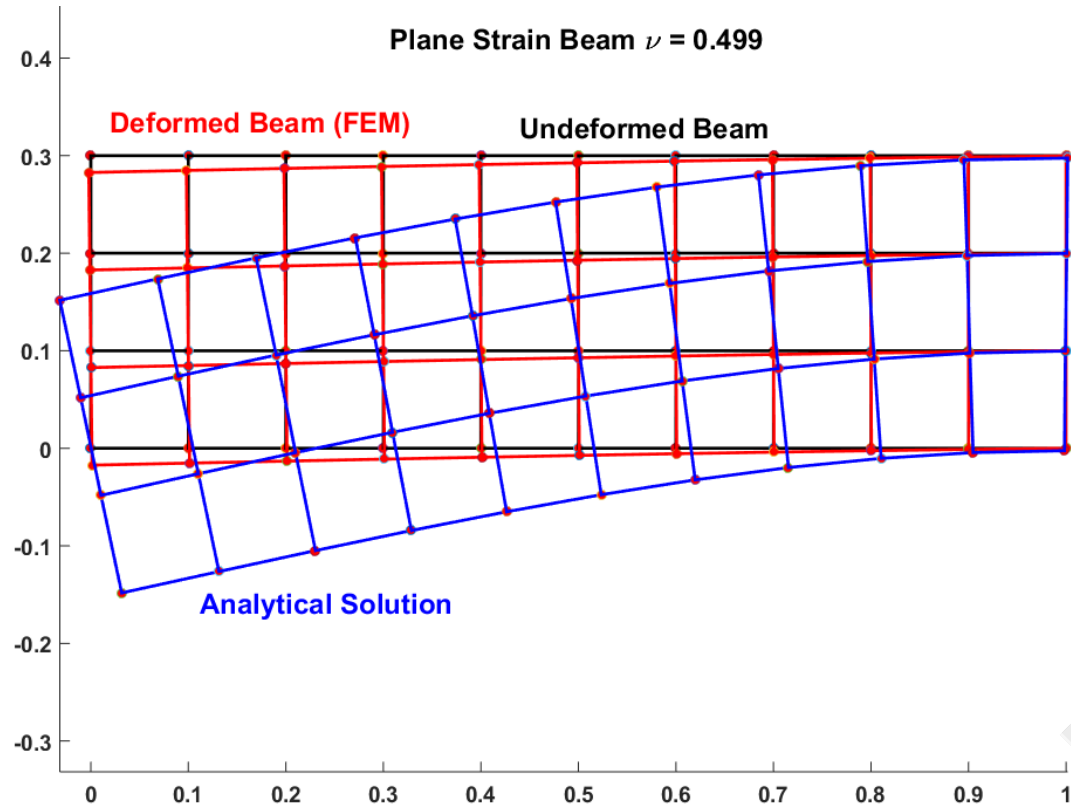
Lecture 55 : Nearly Incompressible Material

Concepts Covered

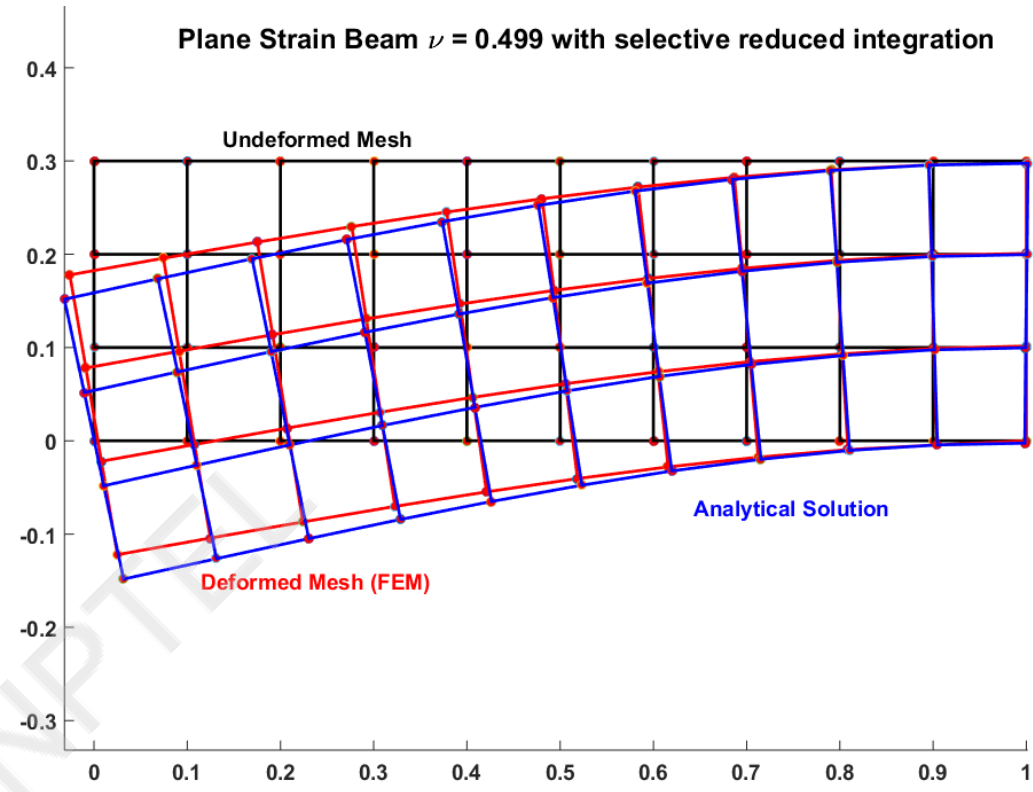
- Volumetric Locking
- Selective Reduced Integration



Plane Strain Beam $\nu = 0.499$



Plane Strain Beam $\nu = 0.499$ with selective reduced integration



Isotropic Case:

plane strain case:

$$C = \frac{E}{(1+\nu)(1-2\nu)} \begin{bmatrix} 1-\nu & \nu & 0 \\ \nu & 1-\nu & 0 \\ 0 & 0 & \frac{1-2\nu}{2} \end{bmatrix}$$

$$C = \begin{bmatrix} \lambda+2\mu & \lambda & \nu \rightarrow 0.5 \\ \lambda & \lambda+2\mu & 0 \\ 0 & 0 & \mu \end{bmatrix}$$

$$\lambda = \frac{E\nu}{(1+\nu)(1-2\nu)}$$

$$\frac{\lambda}{\mu} \rightarrow \infty \text{ as } \nu \rightarrow 0.5$$

$$\mu = \frac{E}{2(1+\nu)}$$

$$C = \begin{bmatrix} \kappa + \frac{4}{3}\mu & \kappa - \frac{2}{3}\mu & 0 \\ \kappa - \frac{2}{3}\mu & \kappa + \frac{4}{3}\mu & 0 \\ 0 & 0 & \frac{2}{3}\mu \end{bmatrix}$$

κ = Bulk modulus

$$= \frac{E}{3(1-2\nu)}$$

$$= \kappa \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} + \mu \begin{bmatrix} \frac{4}{3} & -\frac{2}{3} & 0 \\ -\frac{2}{3} & \frac{4}{3} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \underline{\kappa C_K} + \underline{\mu C_M}$$

$$C = \begin{bmatrix} \lambda+2\mu & \lambda & 0 \\ \lambda & \lambda+2\mu & 0 \\ 0 & 0 & \mu \end{bmatrix} = \lambda \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} + \mu \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \lambda C_\lambda + \mu C_\mu$$

$$[K^e] = \int_{\Omega^e} B^T C B d\Omega^e$$

$$= \int_{\Omega^e} B^T \lambda C_\lambda B d\Omega^e + \int_{\Omega^e} B^T \mu C_\mu B d\Omega^e$$

$$= \lambda \int_{\Omega^e} B^T C_\lambda B d\Omega^e + \mu \int_{\Omega^e} B^T C_\mu B d\Omega^e$$

$$= \lambda [K_\lambda^e] + \mu [K_\mu^e]$$

$$[K^e] \{u^e\} = \{f^e\}$$

$$(\lambda [K_\lambda] + \mu [K_\mu]) \{u^e\} = \{f^e\}$$

$$(\lambda [K_\lambda] + \mu [K_\mu]) \{u\} = \{F\}$$

$$\Rightarrow \{u\} = (\lambda [K_\lambda] + \mu [K_\mu])^{-1} \{F\}$$

$$= \left[\lambda \sum [K_\lambda] + \mu \sum [K_\mu] \right]^{-1} \{F\}$$

$$= \frac{1}{\lambda} \left[[K_\lambda] + \left(\frac{\mu}{\lambda} \right) [K_\mu] \right]^{-1} \{F\}$$

$$\leq \frac{1}{\lambda} [K_\lambda]^{-1} \{F\}$$

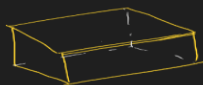
$$K = (\lambda [K_\lambda] + \mu [K_\mu])$$

$$\frac{\lambda}{\mu} \gg \gg 1$$

$$\nu \rightarrow 0.5, \quad \frac{\lambda}{\mu} \rightarrow \infty$$

$$\frac{\lambda}{\mu} = \frac{\frac{E\nu}{(1+\nu)(1-2\nu)}}{\frac{E}{2(1+\nu)}} = \frac{2\nu}{1-2\nu}$$

$$\begin{bmatrix} x & x \\ x & x \end{bmatrix} \quad \begin{matrix} 2 \times 2 \\ 1 \times 1 \end{matrix}$$



$$C = \begin{bmatrix} \lambda+2\mu & \lambda & \lambda & 0 & 0 & 0 \\ \lambda & \lambda+2\mu & \lambda & 0 & 0 & 0 \\ 0 & \lambda & \lambda+2\mu & 0 & 0 & 0 \\ 0 & 0 & 0 & \lambda & 0 & 0 \\ 0 & 0 & 0 & 0 & \lambda & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{2}{3}\mu \end{bmatrix} = \lambda C_\lambda + \mu C_\mu$$

$$K = \lambda K_\lambda + \mu K_\mu$$

$$\downarrow \quad \downarrow$$

$$K = B K_B + \mu K_\mu$$

$$\downarrow \quad \downarrow$$

$$B = \frac{E}{3(1-2\nu)}$$

$$\nu \rightarrow 0.5, \quad B \rightarrow \infty$$

$$\text{nonlinear} \quad \sum \quad F = \det(F) \leq 1$$

$$C = \begin{bmatrix} c_{11} & c_{12} & 0 \\ c_{12} & c_{22} & 0 \\ 0 & 0 & c_{33} \end{bmatrix}$$

$$E_1, E_2, \nu_{12}, G_{12}$$



**THANK
YOU !**



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Module 11: Volumetric Locking

Lecture 56 : B-Bar Method

Concepts Covered

- B-Bar method – Strain projection method



**THANK
YOU !**